

① Let \hat{G} denote all irreducible representations of G

By what we have proved part of $\{\chi_\rho, \rho \in \hat{G}\}$ form an orthonormal basis of $L^2(G)$

\Rightarrow we may write them as $\{\chi_{\phi_i}\}_{i \in \mathbb{N}}$

Now, $\forall \rho$ $\rho = \sum m(\rho, \phi_i) \phi_i$ $m(\rho, \phi_i)$ is the multiplicity.

$\Rightarrow \chi_\rho = \sum m(\rho, \phi_i) \chi_{\phi_i}$

$\int \chi_\rho \cdot \bar{\chi}_{\phi_j} = m(\rho, \phi_j)$

If ρ & ψ are two representations

$\chi_\rho = \chi_\psi \Rightarrow m(\rho, \phi_j) = m(\psi, \phi_j) \quad \forall j$

$\Rightarrow \rho = \psi$

Moreover if $\int \chi_\rho \bar{\chi}_\rho = 1$ $\chi_\rho = \sum m(\rho, \phi_i) \chi_{\phi_i}$

$\Rightarrow \sum m(\rho, \phi_i)^2 = 1 \Rightarrow$ only one of them say $m(\rho, \phi_{i_0}) = 1$

& $\rho = \phi_{i_0} \Rightarrow \rho$ is irreducible.

This completes the proof of Thm 3 of last lecture.

Thm 2 fails if G is Not Compact.

e.g. $G = \left\{ \begin{pmatrix} a & b \\ 0 & c \end{pmatrix} \right\}$

②

Quaternions: $\left[\begin{array}{l} \text{Cross product} \\ \rightarrow v_i \times (v_2 \times v_3) = \langle v_i, v_3 \rangle v_2 - \langle v_i, v_2 \rangle v_3 \\ \text{This can be checked by brutal force computation} \end{array} \right]$

$$\Rightarrow v_i \times (v_2 \times v_3) = \langle v_i, v_3 \rangle v_2 - \langle v_i, v_2 \rangle v_3 + v_2 \times (v_3 \times v_1) + \langle v_2, v_1 \rangle v_3 - \langle v_2, v_3 \rangle v_1 = 0 + v_3 \times (v_1 \times v_2) + \langle v_3, v_2 \rangle v_1 - \langle v_3, v_1 \rangle v_2$$

Namely (\mathbb{R}^3, \times) is a Lie algebra.

$$q = a + bj$$

$$\bar{q} = \bar{a} - j\bar{b}$$

$i^2 = -1$
 $j^2 = -1$
 $k^2 = -1$
 $ij = k$
 $ji = -k$
 $jk = i$
 $kj = -i$
 $ki = j$
 $ik = -j$

$$q = x + iy + jz + kw$$

$$q(t) = x(t) + iy(t) + jz(t) + kw(t)$$

$$\bar{q} = x - iy - jz - kw$$

$$= (x - iy) - j(z + iw)$$

Consider unit quaternions

$$x^2 + y^2 + z^2 + w^2 = 1$$

$$\begin{vmatrix} i & j & k \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix} = \begin{vmatrix} x_2 & x_3 \\ y_2 & y_3 \end{vmatrix} i + \dots$$

$$q \cdot \bar{q} = (z_1 + z_2 j)(\bar{z}_1 - j\bar{z}_2)$$

$$= z_1 \bar{z}_1 - z_1 z_2 j + z_2 z_1 j + z_2 \bar{z}_2$$

$$= |z_1|^2 + |z_2|^2$$

$$jz = j(x + iy) = jx - ky = (bx - iy)j = \bar{z}j$$

$$q_1 \cdot \bar{q}_2 + q_2 \cdot \bar{q}_1$$

$$\begin{aligned} & (z_1 + z_2 j)(\bar{w}_1 - j\bar{w}_2) + (w_1 + w_2 j)(\bar{z}_1 - j\bar{z}_2) \\ &= z_1 \bar{w}_1 - z_1 w_2 j + z_2 w_1 j + z_2 \bar{w}_2 + w_1 \bar{z}_1 - z_2 w_1 j + w_2 z_1 j + w_2 \bar{z}_2 \\ &= \boxed{z_1 \bar{w}_1 + w_1 \bar{z}_1 + z_2 \bar{w}_2 + w_2 \bar{z}_2} \\ &= (a_1 + ib_1)(\tilde{a}_1 - i\tilde{b}_1) + (a_1 + i\tilde{b}_1)(a_1 - i\tilde{b}_1) \\ &+ (c_1 + id_1)(\tilde{c}_1 - i\tilde{d}_1) + (c_1 + i\tilde{d}_1)(c_1 - i\tilde{d}_1) \\ &= 2(a_1 \tilde{a}_1 + b_1 \tilde{b}_1 + c_1 \tilde{c}_1 + d_1 \tilde{d}_1) \end{aligned}$$

Namely $\boxed{q_1 \cdot \bar{q}_2 + q_2 \cdot \bar{q}_1} = 2 \langle \mathcal{R}(q_1), \mathcal{R}(q_2) \rangle$

$$\mathcal{R}(q_1) = \begin{pmatrix} a_1 \\ b_1 \\ c_1 \\ d_1 \end{pmatrix} \quad q_1 = a_1 + ib_1 + (c_1 + di_1)j$$

$$a^2 + b^2 + c^2 + d^2 = 1$$

$$\frac{(q_1 \cdot q_2)(q_1 \cdot \bar{q}_2)}{q_1 \cdot \bar{q}_1} = \frac{q_1 \cdot \bar{q}_2}{q_1 \cdot \bar{q}_1} = \frac{q_1 \cdot \bar{q}_2}{1} = q_1 \cdot \bar{q}_2 = 1$$

$$|q|^2 = 1 \Leftrightarrow q = a + ib + (c + di)j = a + ib + jc + dk$$

$a, b, c, d \in \mathbb{R}$

Now $0 = \overline{q'(t)} \cdot \overline{q(t)} + \underline{q(t)} \cdot \overline{q'(t)}$ $\overline{q(t)} \cdot \overline{q'(t)} = 1$ $\underline{q(t)} \cdot \underline{q'(t)} = 1$

$\Rightarrow \underline{q'(t)} \Big|_{t=0} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ $y'(0)i + z'(0)j + w'(0)k$ namely $x'(0) = 0$

$\Rightarrow \underline{q}$ near 1 can be written as

$\underline{1 + \underline{q}' + o(2)}$ $\underline{q}' = ai + bj + ck$

Now we use $x - y$ for \underline{q}

$x \cdot y - y \cdot x$ for x, y near 1.

Recall, $\begin{cases} \psi(x, y) = x^\alpha y^\beta + b_{pr} x^p y^r + \text{higher} \\ \psi(y, x) = y^\alpha x^\beta + b_{pr} y^p x^r \end{cases}$

$\Rightarrow \psi(x, y) - \psi(y, x) = C_{pr} x^p y^r + \dots$

To our case $\begin{matrix} x(t) \\ \parallel \\ (1 + x' + o(2)) \end{matrix} \begin{matrix} y(t) \\ \parallel \\ (1 + y' + o(2)) \end{matrix} - \begin{matrix} y(t) \\ \parallel \\ (1 + y' + o(2)) \end{matrix} \begin{matrix} x(t) \\ \parallel \\ (1 + x' + o(2)) \end{matrix}$

$= 1 + y' + x' + x' \cdot y' + o(2) - (1 + y' + x' + y' \cdot x' + o(2))$

$= \underline{x' \cdot y' - y' \cdot x' + o(2)}$

$= (a_1 i + b_1 j + c_1 k) \cdot (a_2 i + b_2 j + c_2 k) - (a_2 i + b_2 j + c_2 k) \cdot (a_1 i + b_1 j + c_1 k) + o(2)$

$= -\underbrace{(a_1 a_2 + b_1 b_2 + c_1 c_2)} + (a_1 b_2 - b_1 a_2)k + (a_1 c_2 - a_2 c_1)j + (-a_2 b_2 + c_2 b_1)i$

$= -[(a_1 c_2 + b_1 b_2 + c_1 c_2) + \text{Swap}]$

$= 2 \begin{pmatrix} a_1 \\ b_1 \\ c_1 \end{pmatrix} \times \begin{pmatrix} a_2 \\ b_2 \\ c_2 \end{pmatrix}$

$$\begin{vmatrix} i & j & k \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}$$

If we renormalize \mathfrak{g}' , we get the (\mathbb{R}^3, \times) as the Lie algebra

Namely $\mathcal{S}^3 = \{ \underline{g} \mid |\underline{g}| = 1 \}$ has (\mathbb{R}^3, \times) as its Lie algebra.

$$\underline{g}_1 \cdot \underline{g}_2 = (z_1 + v_1 j)(z_2 + v_2 j) = z_1 z_2 + z_1 v_2 j + v_1 \bar{z}_2 j - v_1 \bar{v}_2$$

$$\bar{\underline{g}}_2 \cdot \bar{\underline{g}}_1 = (\bar{z}_2 - j \bar{v}_2)(\bar{z}_1 - j \bar{v}_1) = \bar{z}_2 \bar{z}_1 - j \bar{z}_2 \bar{v}_1 - j \bar{v}_2 \bar{z}_1 - \bar{v}_2 \bar{v}_1$$

$$\Rightarrow \overline{\underline{g}_1 \cdot \underline{g}_2} = \bar{\underline{g}}_2 \cdot \bar{\underline{g}}_1$$

Hence if $|\underline{g}_1| = |\underline{g}_2| = 1 \Rightarrow (\underline{g}_1 \cdot \underline{g}_2)(\bar{\underline{g}}_2 \cdot \bar{\underline{g}}_1) = 1$.

Namely \mathcal{S}^3 is a Lie group.

We shall study its representation!

(1st interesting one $\begin{matrix} n=1 \\ =2 \end{matrix}$ connected Lie groups can be decided.)
& nontrivial.

It holds the key for the high dimensional study as well.

$$\textcircled{3} \quad SU(2) \cong \mathcal{S}^3 \subset \mathbb{R}^4 = \mathbb{C}^2$$

$$\underline{g} = w_1 + w_2 j \in \mathbb{H} \quad \text{(quaternions)}$$

For $\underline{g}' = z_1 + j z_2$ we view it as \mathbb{C}^2

$$\begin{pmatrix} z_1 + j z_2 \\ z_1 \end{pmatrix} \lambda = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \lambda$$

$\lambda \in \mathbb{C}$ acts from the right

$C(\underline{g})$ will be the matrix representation of \underline{g} acts from left

$$\begin{aligned} \underline{g} (\underline{w}_1 + w_2 j) (\underline{z}_1 + j \underline{z}_2) &= w_1 z_1 + w_1 j z_2 + w_2 j z_1 - w_2 z_2 \\ &= \underbrace{w_1 z_1 - w_2 z_2} + j (\bar{w}_1 z_2 + \bar{w}_2 z_1) \\ C(\underline{g}) \cdot \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} &= \begin{pmatrix} w_1 z_1 - w_2 z_2 \\ \bar{w}_1 z_2 + \bar{w}_2 z_1 \end{pmatrix} \end{aligned}$$

$$C(\mathfrak{g}) = \begin{pmatrix} w_1 & -w_2 \\ \bar{w}_2 & \bar{w}_1 \end{pmatrix} \quad \mathfrak{g} \in \mathfrak{S}^3$$

$$\det(C(\mathfrak{g})) = 1 \quad \& \quad C(\mathfrak{g}) \cdot \overline{C(\mathfrak{g})}^t = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$C(\mathfrak{g}_1 \cdot \mathfrak{g}_2) = \begin{pmatrix} w_1 \tilde{w}_1 - w_2 \tilde{w}_2 & -(w_1 \tilde{w}_2 + w_2 \tilde{w}_1) \\ \overline{w_1 \tilde{w}_2 + w_2 \tilde{w}_1} & \overline{w_1 \tilde{w}_1 - w_2 \tilde{w}_2} \end{pmatrix} \quad \left(\begin{matrix} C(\mathfrak{g}_1) \cdot C(\mathfrak{g}_2) \\ \left(\begin{matrix} w_1 & -w_2 \\ \bar{w}_2 & \bar{w}_1 \end{matrix} \right) \left(\begin{matrix} \tilde{w}_1 & -\tilde{w}_2 \\ \bar{\tilde{w}}_2 & \bar{\tilde{w}}_1 \end{matrix} \right) \end{matrix} \right)$$

$$\uparrow$$

$$(w_1 + w_2 j) \cdot (\tilde{w}_1 + \tilde{w}_2 j)$$

$$= w_1 \tilde{w}_1 + w_1 \tilde{w}_2 j + w_2 \tilde{w}_1 j - w_2 \tilde{w}_2$$

$$\text{Namely } C(\mathfrak{g}_1 \cdot \mathfrak{g}_2) = C(\mathfrak{g}_1) \cdot C(\mathfrak{g}_2)$$

$$C: \mathfrak{S}^3 := \{ \mathfrak{g} \in \mathbb{Q} \mid |\mathfrak{g}| = 1 \} \longrightarrow SU(2)$$

is a group homomorphism.

Since $\forall A = \begin{pmatrix} z_1 & z_2 \\ z_3 & z_4 \end{pmatrix} \in SU(2)$, it can be checked

$$z_3 = -\bar{z}_2 \quad z_4 = \bar{z}_1$$

$$\Rightarrow A = C(\mathfrak{g}) \text{ with } \mathfrak{g} = z_1 + z_2 j$$

$\Rightarrow C$ is an isomorphism.

Let $V_k :=$ degree k -polynomial of z_1, z_2

$$\text{Span} \{ z_1^k, z_1^{k-1} z_2, \dots, z_1 z_2^{k-1}, z_2^k \}$$

$$\dim V_k = k+1.$$

$\mathfrak{S}^3 = \{ \mathfrak{g} \mid \mathfrak{g} = a + bj, |\mathfrak{g}| = 1 \}$ acts on V_k via

$$C(\mathfrak{g})$$

$$\begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \rightarrow \begin{pmatrix} a & -b \\ \bar{b} & \bar{a} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} z_1' \\ z_2' \end{pmatrix}$$

Theorem 1: Let ϕ_k be the induced representation of \mathbb{S}^3 on V_k .
Then $\{\phi_k\}$ are all the irreducible representations of $\mathbb{S}^3 = \text{SU}(2)$.

(4) Proof.

The character theory reduces the study of the representation to the study of character functions.

(e.g) $G = \mathbb{S}^1$ $e^{i\theta}$

$\phi_k: G \rightarrow \text{GL}(1, \mathbb{C})$ $e^{i\theta} \rightarrow (z \rightarrow \underbrace{e^{ik\theta}}_z)$

$\chi_{\phi_k} = e^{ik\theta}$ $\frac{1}{2\pi} \int_{\mathbb{S}^1} |\chi_{\phi_k}|^2 d\theta = 1$

$\frac{1}{2\pi} \int_0^{2\pi} 1 d\theta = 1$

$\int \chi_{\phi_k} \overline{\chi_{\phi_l}} = 0$ $dn = \frac{1}{2\pi} d\theta$

Moreover $\left\{ \chi_{\phi_k} \right\}_{k \in \mathbb{Z}}$ is a complete basis in $L^2(\mathbb{S}^1)$

\Rightarrow Any $\chi_\psi = \sum c_k \chi_{\phi_k} \Rightarrow$ We obtained all representations.

We use similar idea in the proof of Theorem 1.

Remark: $\phi \otimes \psi$ $\phi: G \rightarrow \text{GL}(r, v)$

$\psi: G \rightarrow \text{GL}(r', w)$

$V \otimes W$ generated by $e_i \otimes E_j$ $\{e_i\}$ $\{E_j\}$
 basis of $V \otimes W$ basis of V (W)
 $1 \leq i, h \leq r$ $1 \leq j, l \leq r'$ $\dim(V \otimes W) = n \times m$

$\phi(g)(e_i) = e_k \phi_{ki}$
 $\psi(g)(E_j) = E_l \psi_{lj}$
 $\chi_{\phi(g)} = \sum_{k=1}^n \phi_{kk}(g)$
 $\chi_{\psi(g)} = \sum_{l=1}^m \psi_{ll}(g)$

$\chi_{\phi \otimes \psi}(g) := \langle e_s^* \otimes E_t^*, \phi \otimes \psi(e_s \otimes E_t) \rangle$

$= \langle e_s^* \otimes E_t^*, \phi_{ks} \psi_{lt} e_k \otimes E_l \rangle$
 $= \sum \phi_{kk} \psi_{ll} = \chi_{\phi} \cdot \chi_{\psi}$

The general fact: The maximum tori intersects every conjugacy class.
 Namely $\forall x \in G \quad \exists g \in T \quad \{g x g^{-1}, g \in G\}$
 $x \in G$

This is a result of Cartan. $\chi(x) = \chi(g x g^{-1}) = \chi(t) \quad t \in T$

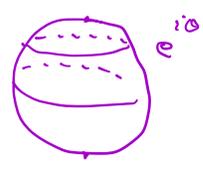
In this special case, we exam. the conjugacy class of

$e^{i\theta} = \cos\theta + i \sin\theta$

$g = a + bj$

$|g|^2 = 1$

$g(\cos\theta + i \sin\theta) \bar{g} = \cos\theta + \frac{g(i \sin\theta) \bar{g}}{1}$
 $= \cos\theta + \frac{\sin\theta}{1} g(i) \bar{g}$



$(a + bj) i (\bar{a} - j \bar{b}) = i(|a|^2 - |b|^2) + (-i b a) j + (i a b) j$
 $= i(|a|^2 - |b|^2) + (-2abi)j$

Hence $g(\cos\theta + i \sin\theta) \bar{g} = \cos\theta + \frac{\sin\theta}{c + dj} [i(|a|^2 - |b|^2) - (2abi)j]$

$(a, b) \in \mathbb{S}^3 \rightarrow (|a|^2 - |b|^2, -2ab)$
 $|a|^2 + |b|^2 = 1$ is a fibration of $\mathbb{S}^3 \rightarrow \mathbb{S}^2$

$(|a|^2 - |b|^2)^2 + 4|a|^2 |b|^2 = 1$

Hence the conjugacy class of $e^{i\theta}$ is a

2-sphere with radius $\sin\theta$

(the conjugacy class)
except the case $\sin\theta=0$

$$\phi_1(e^{i\alpha}) = \begin{pmatrix} e^{i\alpha} & 0 \\ 0 & e^{-i\alpha} \end{pmatrix}$$

$V_k = \text{Span}$

$$\Rightarrow \begin{cases} \phi_1(z_1) = e^{i\alpha} z_1 \\ \phi_1(z_2) = e^{-i\alpha} z_2 \end{cases} \Rightarrow \phi_h \text{ action on } \dots$$

$$\{z_1^k, z_1^{k-1} z_2, \dots, z_1 z_2^{k-1}, z_2^k\}$$

$$\begin{bmatrix} e^{ik\theta} & e^{i(k-2)\theta} & \dots & e^{-i(k-2)\theta} & e^{-ik\theta} \end{bmatrix}$$

$$\chi_{\phi_k}(e^{i\theta}) = \frac{e^{i(k+1)\theta} - e^{-i(k+1)\theta}}{e^{i\theta} - e^{-i\theta}}$$

$$(1) \begin{bmatrix} e^{ik\theta} & & & \\ & e^{i(k-2)\theta} & & \\ & & \dots & \\ & & & e^{-ik\theta} \end{bmatrix}$$

Note $|\underline{q} \cdot \underline{x}|^2 = \underline{q} \cdot \underline{x} \cdot \bar{\underline{x}} \cdot \bar{\underline{q}} = |\underline{x}|^2 \Rightarrow$
 $\underline{q} \in \mathbb{S}^3$

$R_{\underline{q}}, L_{\underline{q}}$
are isometry on \mathbb{S}^3

\Rightarrow The du on \mathbb{S}^3 is just the standard round metric. $\frac{1}{2\pi^2}$
volume

(since $|\mathbb{S}^3| = \int_0^\pi 4\pi \sin^2\theta d\theta = 2\pi^2$)

$$\sin^2\theta = \frac{1}{4} |e^{i\theta} - e^{-i\theta}|^2 \quad (2)$$

$$\Rightarrow \int_{\mathbb{S}^3} |\chi_{\phi_k}|^2 du = \int_0^\pi |\chi_{\phi_k}|^2 \cdot \frac{1}{2\pi^2} \cdot \frac{4\pi \sin^2\theta d\theta}{\frac{1}{4} |e^{i\theta} - e^{-i\theta}|^2}$$

use (1) & (2)

$$= \frac{1}{\pi} \int_0^{2\pi} |\chi_{\phi_k}|^2 \frac{|e^{i\theta} - e^{-i\theta}|^2}{4} d\theta = 1$$

(= $\frac{1}{4\pi} \int_0^{2\pi} |e^{i(k+1)\theta} - e^{-i(k+1)\theta}|^2 d\theta = 1$)

Similarly $\int_{\mathbb{S}^3} \chi_{\phi_k} \bar{\chi}_{\phi_l} = 0$ if $k \neq l$.

Now we know that $\phi_k: \mathbb{S}^3 \rightarrow$ linear transformation induced on V_k

is irreducible

$\forall \psi: \mathbb{S}^3 \rightarrow V$ we consider

$$\int_{\mathbb{S}^3} \chi_\psi \cdot \overline{\chi_{\phi_l}} \, d\mu = \frac{1}{2\pi} \int_0^\pi \chi_\psi(e^{i\theta}) \frac{\overline{\begin{pmatrix} e^{i(l+1)\theta} & -e^{-i(l+1)\theta} \\ e^{i\theta} & -e^{-i\theta} \end{pmatrix}}}{|e^{i\theta} - e^{-i\theta}|^2} \, d\theta$$

$$j e^{i\theta} \overline{j} = e^{-i\theta} \Rightarrow \chi_\psi(e^{i\theta}) = \chi_\psi(e^{-i\theta})$$

$$\text{Hence } \Rightarrow \int_{\mathbb{S}^3} \chi_\psi \cdot \overline{\chi_{\phi_l}} \, d\mu = \frac{1}{2\pi} \int_0^\pi \chi_\psi(e^{i\theta} - e^{-i\theta}) \cdot \frac{\overline{\begin{pmatrix} e^{i(l+1)\theta} & -e^{-i(l+1)\theta} \\ e^{i\theta} & -e^{-i\theta} \end{pmatrix}}}{2 \sin(l+1)\theta} \, d\theta$$

$$\text{If } \langle \chi_\psi, \overline{\chi_{\phi_l}} \rangle = 0 \quad \forall l$$

\Rightarrow The odd function $\boxed{2\chi_\psi(e^{i\theta}) \sin\theta}$ must be zero.

This shows $\phi_k: \mathbb{S}^3 \rightarrow GL(k+1, V_k)$ gives all irreducible representations of \mathbb{S}^3 .